

Technical Note

(tcpgps_windows_hitarget_en_v4_005_setting_up_rover_in_static_mode)

Setting up rover in static mode

Update Date

07/05/2019

Requirements

Hardware:

GNSS receiver: SatLab SL700 / SL900 / SL800
HiTarget V90+ / iRTK5 / V100

Tablet / Laptop: Device with **ARM** processor architecture and **Windows CE** or **Windows Mobile v4+** operating system or device with **x86** processor architecture and **Windows 7 / 8 / 8.1 / 10** operating system

Software:

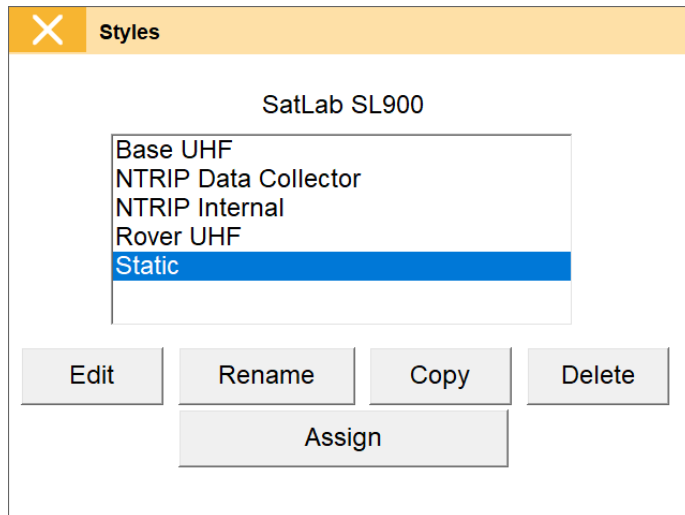
TcpGPS v4.2.5+ for Windows

Objective

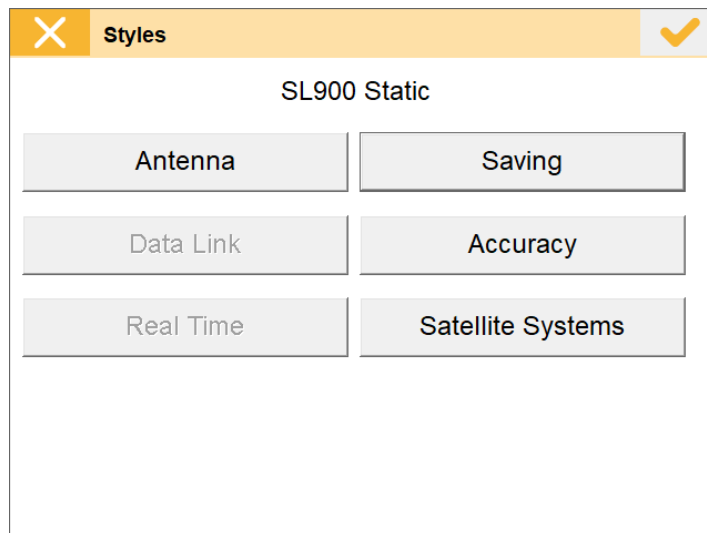
Setting up the rover GNSS receiver in static mode

Details

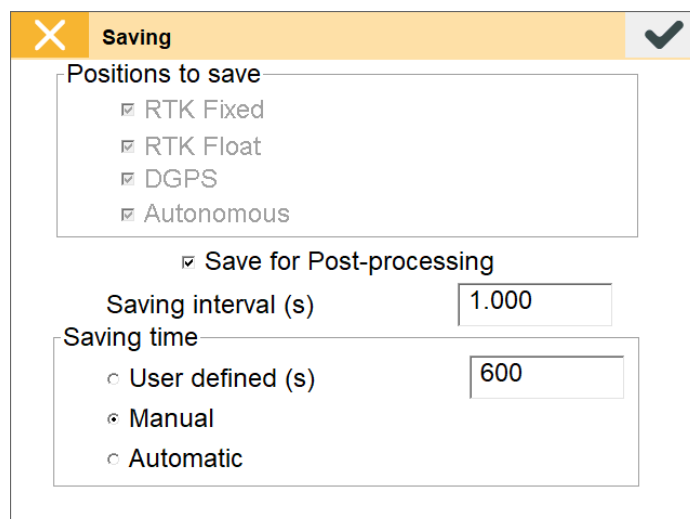
- Run TcpGPS
- Connect to the rover GNSS receiver
- Go to *GPS > Styles*, select *Static* and click on *Edit* button



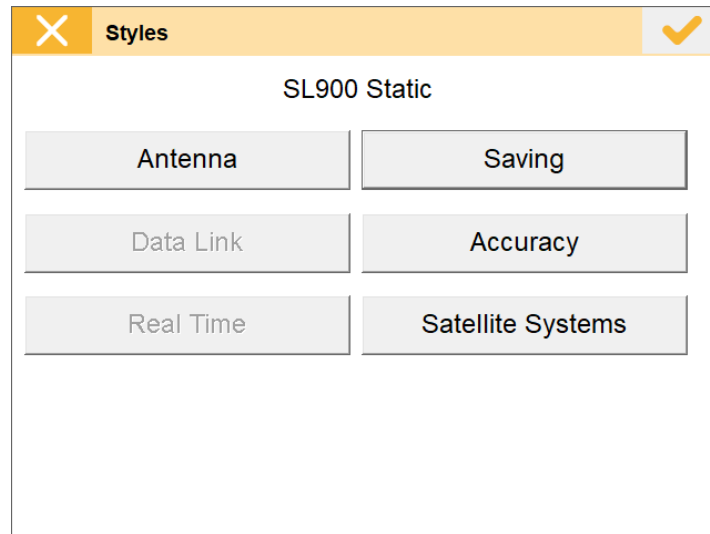
- Click on *Saving* button




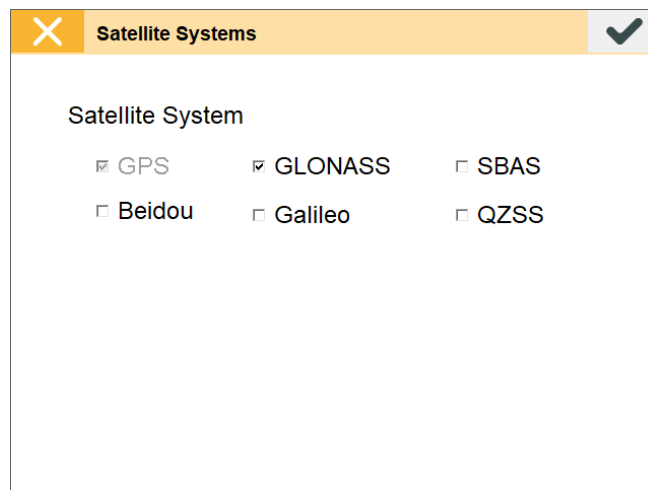
- Enter the recording *interval*, in seconds, and select *Manual* in *Saving time* box. Then, click on accept button ✓




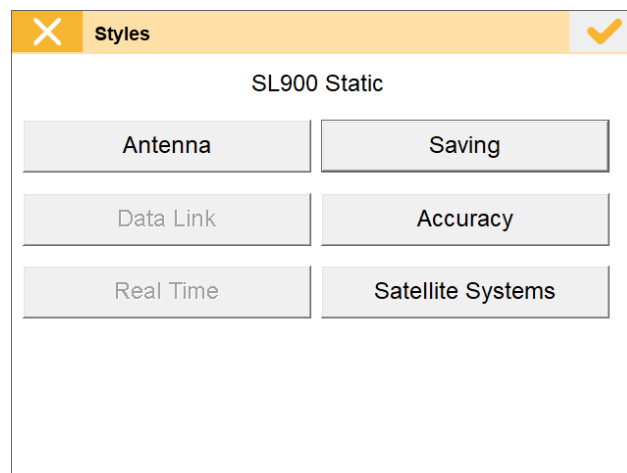
- Click on *Satellite Systems* button



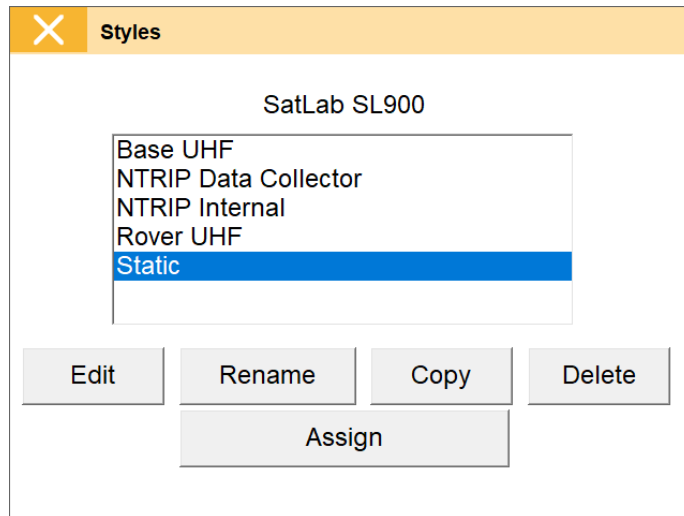
- Select the satellite systems to be used and click on accept button 



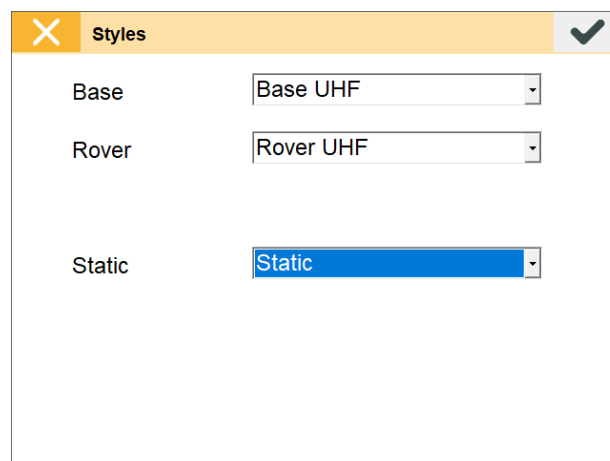
- Click on accept button  to save the changes in the working style



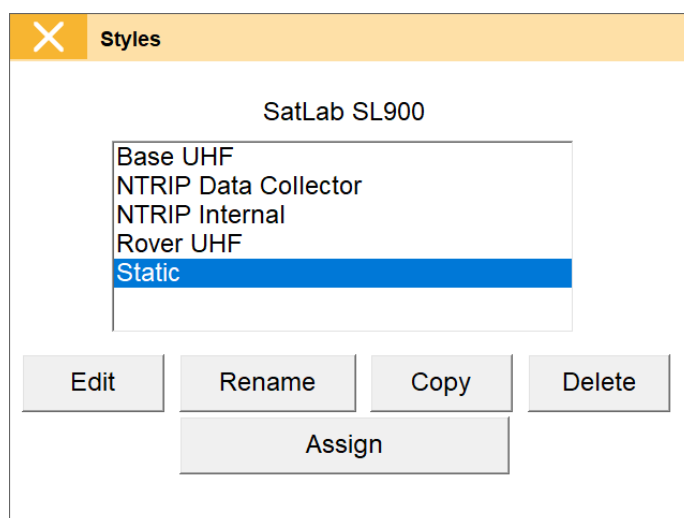
- Click on *Assign* button to select the working style for static mode



- Select the *Static* working style in *Static* list and click on accept button ✓



- Close the working styles screen to return to the main menu



- Go to *Survey* > *Static*, enter the *File* name and click on *Start* button

